



**VANDERBILT**  
School *of* Engineering

# CE 3300-01 – RISK, RELIABILITY, AND RESILIENCE ENGINEERING

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Bayesian Learning

Book Reference: Chapters 2

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# Probability Rules 2 – Recap on Objectives

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- Distinguish probability views
  - Events and Probability
  - Probability Problem Characteristics
- Describe events, outcomes, and corresponding Probabilities
  - Estimating Probabilities
  - Mathematical Operations of Sets
- Calculate marginal, conditional, and joint probabilities
  - The Addition Rule
  - Conditional Probability
  - The Multiplication Rule
  - The Theorem of Total Probability
  - **The Bayes' Theorem**

# Bayesian Learning – Learning Objectives

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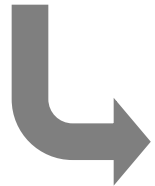


- Discuss Bayesian reasoning
- Explain Bayes Theorem
  - **The Bayes' Theorem**
- Calculating and updating conditional probabilities

# Recall: Epistemic Vs. Aleatory Uncertainty



**Aleatory Uncertainty** – The product of the inherent variability in natural processes.



- An example is the variability of the loads that the structure has to withstand.

**Epistemic Uncertainty** – The result of the lack of enough knowledge or information about the analyzed system

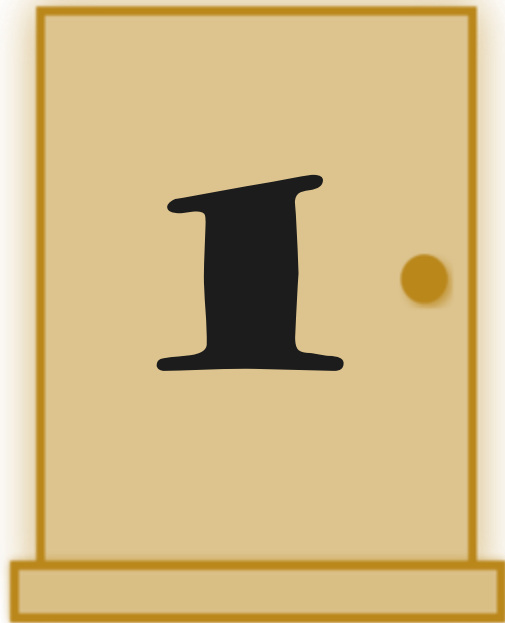


- This lack of information can be produced by deficiency of data or because the structure's behavior is not correctly represented.
- The more knowledge that is available about a structure or system, the more this type of uncertainty can be reduced.

# The Monty Hall Problem



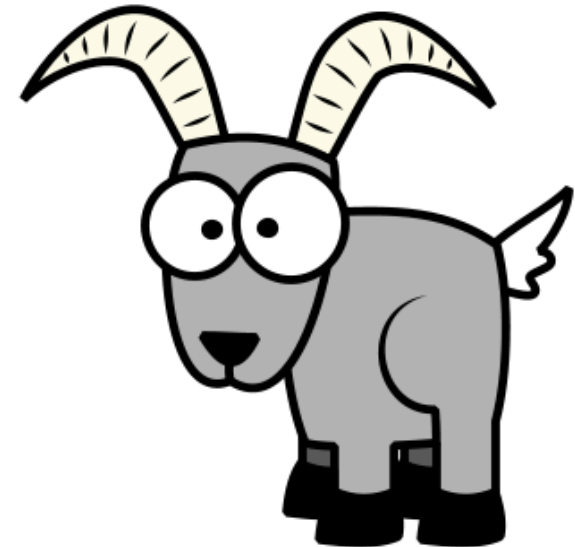
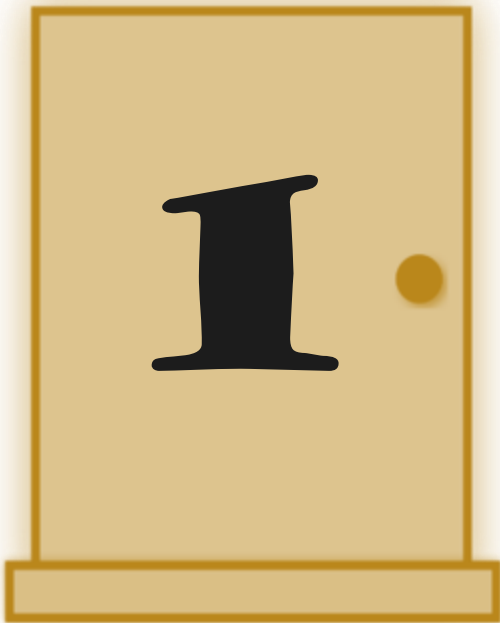
The problem was named after Monty Hall, the host of the American television game show **Let's Make a Deal**.



# The Monty Hall Problem



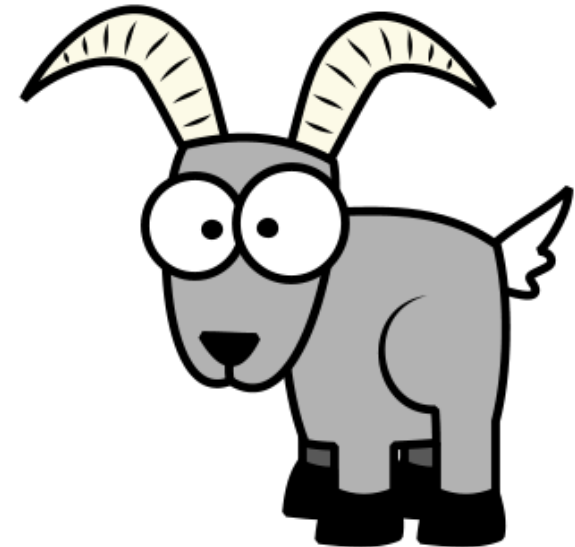
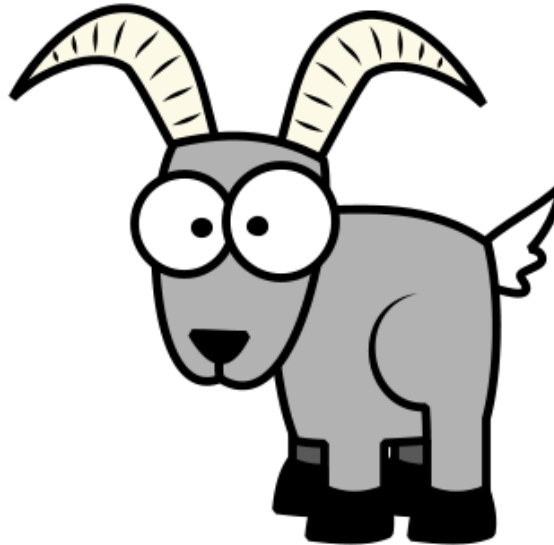
One door is revealed.  
Two choices – either stay or swap



# The Monty Hall Problem



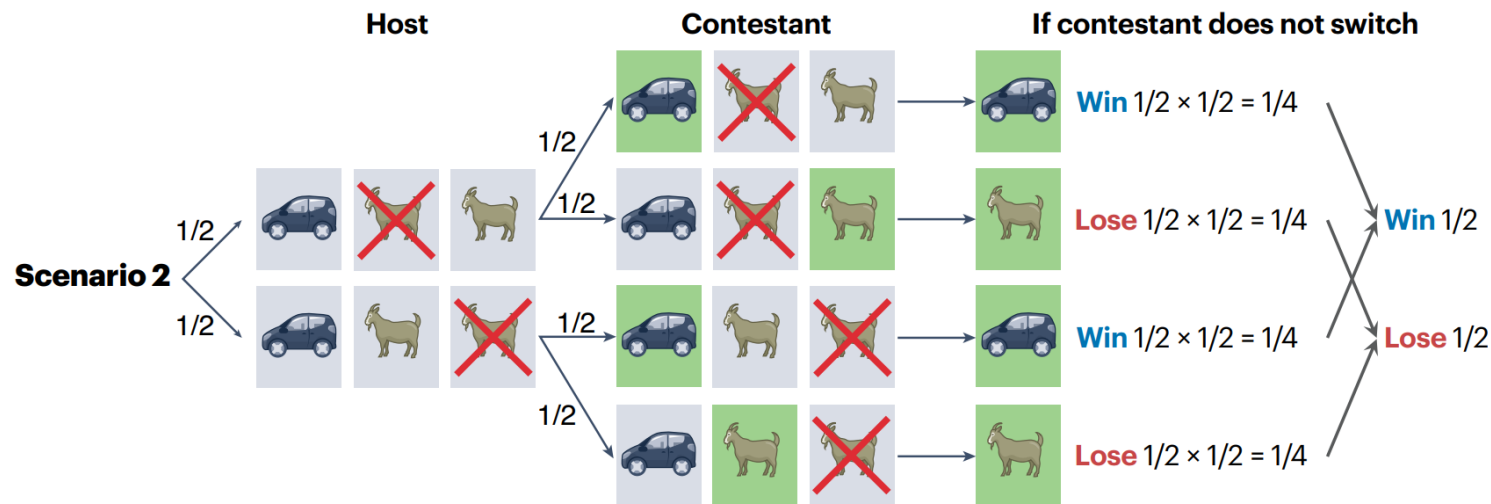
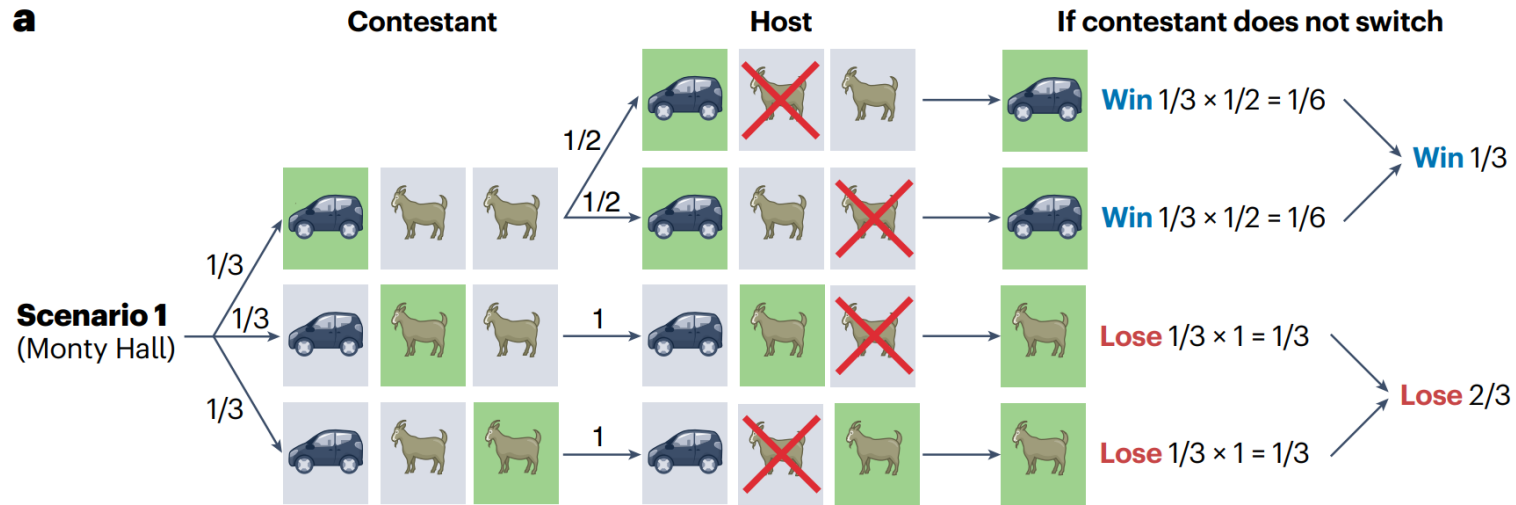
- Would switching increase the contestant's chance of winning?
- What are the probabilities of winning given the **swap or stay** actions?



# Let's Analyze: Two Scenarios



- Order of events matters
- The action after observing a prior event matters

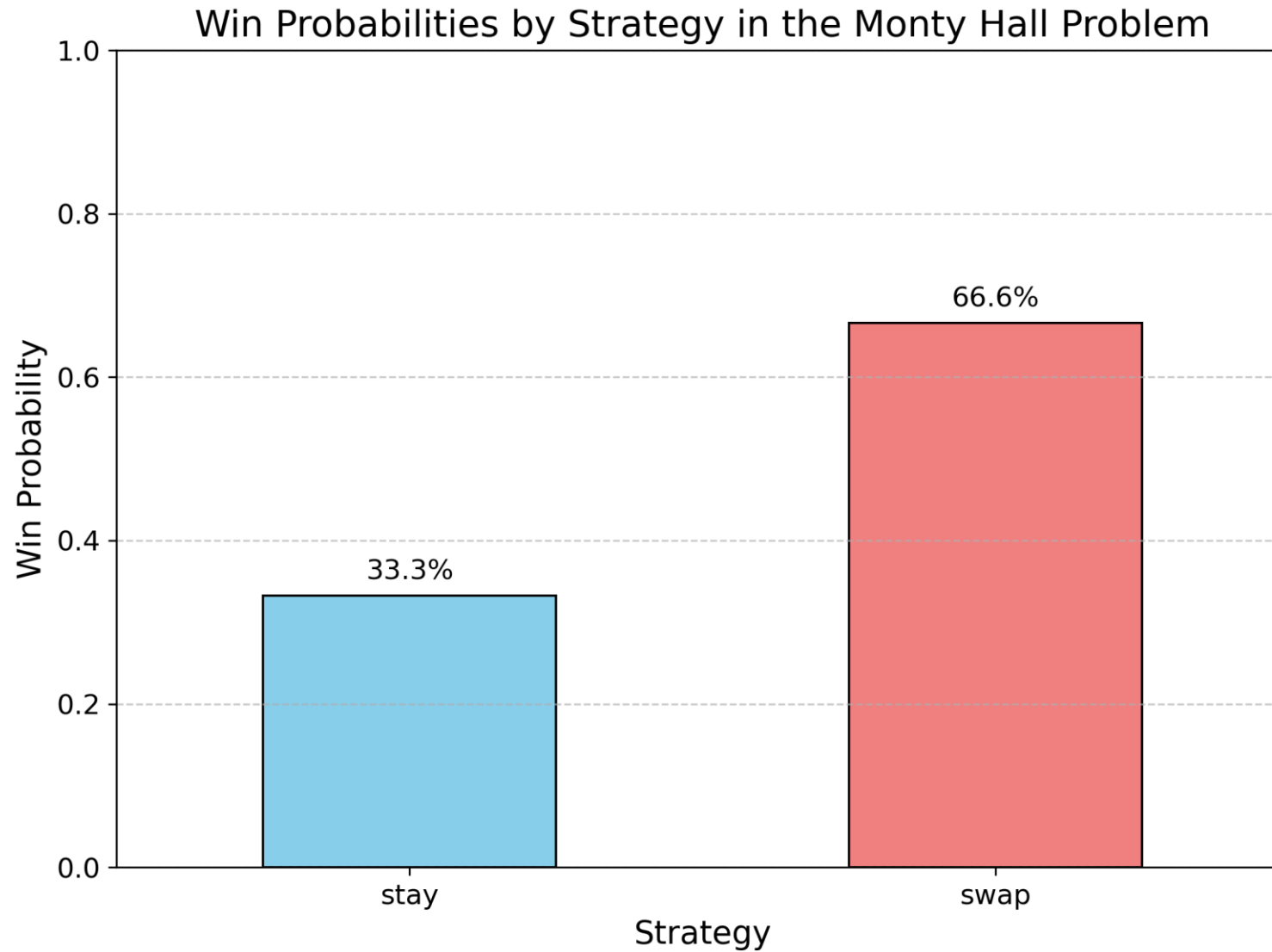


# The Winning Probabilities

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| prize_location | initial_choice | reveal_door | stay_or_swap | final_choice | win   | win_if_swap | win_if_stay |
|----------------|----------------|-------------|--------------|--------------|-------|-------------|-------------|
| 2              | 2              | 1           | swap         | 3            | FALSE | FALSE       | FALSE       |
| 3              | 3              | 2           | stay         | 3            | TRUE  | FALSE       | TRUE        |
| 3              | 3              | 1           | stay         | 3            | TRUE  | FALSE       | TRUE        |
| 1              | 2              | 3           | swap         | 1            | TRUE  | TRUE        | FALSE       |
| 1              | 3              | 2           | stay         | 3            | FALSE | FALSE       | FALSE       |
| 1              | 2              | 3           | swap         | 1            | TRUE  | TRUE        | FALSE       |
| 1              | 2              | 3           | swap         | 1            | TRUE  | TRUE        | FALSE       |
| 1              | 3              | 2           | stay         | 3            | FALSE | FALSE       | FALSE       |
| 1              | 1              | 2           | swap         | 3            | FALSE | FALSE       | FALSE       |

# The winning Probabilities



# Intuition: Frequentist Vs. Bayesian Approach



The difference is in the interpretation of uncertainty.

- Observed phenomena are generated by an unknown but fixed process.
- Population parameters are unknown constants, given that complete and exact knowledge about the sample space is not available.

- Bayesian statistics assumes that population parameters, though unknown, are quantifiable random variables.
- Uncertainty about them can be described by probability distributions

# Bayes' Theorem



x: "hidden variable", the estimate  
y: observations, measurements, data

$$p(\mathbf{x} \mid \mathbf{y}) = \frac{p(\mathbf{y} \mid \mathbf{x})p(\mathbf{x})}{p(\mathbf{y})}$$

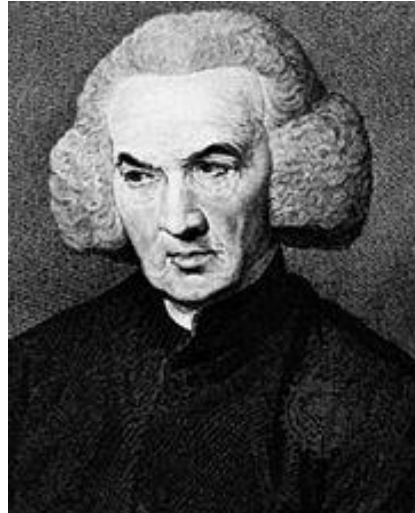
- $p(\mathbf{x} \mid \mathbf{y})$  is the **posterior probability**, function of  $\mathbf{y}$
- $p(\mathbf{x})$  is the **prior or marginal probability** of  $\mathbf{x}$ ; prior in the sense that it does not take into account the data.
- $p(\mathbf{y})$  is a **normalizing factor**, the data.
- $p(\mathbf{y} \mid \mathbf{x})$  is the **likelihood of the observation  $\mathbf{y}$  given  $\mathbf{x}$**

# A Bit of History

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“An essay towards solving a problem  
in the Doctrine of Chances”  
(1763)



# A Bit of History



- First publication of Bayesian methods for applied scientists: 1963
- Bayesian statistics is a way of thinking

## FiveThirtyEight

Politics Sports **Science** Podcasts Video





MAR. 17, 2014, AT 4:57 PM

### How Statisticians Could Help Find That Missing Plane

By [Carl Bialik](#)



Two Royal Malaysian Navy vessels conduct a search and rescue operation for the missing Malaysia Airlines plane over the Straits of Malacca, Malaysia, Thursday, March 13, 2014. THE ROYAL MALAYSIAN NAVY / AP

the theory   that would not die  how bayes' rule cracked the enigma code, hunted down russian submarines & emerged triumphant from two  centuries of controversy sharon bertsch mcgrayne

*"If you're not thinking like a Bayesian, perhaps you should be."  
—John Allen Paulos, New York Times Book Review*

# Example 1 – Monty Hall: A Bayesian Approach



Scenario:

1. You select one of the doors, say Door A.
2. The host, who knows what is behind each door, then opens one of the two remaining doors (e.g., Door B) to reveal a goat.
3. You are then offered a choice: either stick with your original selection (Door A) or switch to the other unopened door (Door C).

Using Bayes' theorem,

1. Determine if you should stick with your initial choice or switch doors to maximize your chances of winning.
2. Calculate the probability of winning in each case.

# Example 1 – Monty Hall: A Bayesian Approach



$$P(H | E) = \frac{P(E|H)P(H)}{P(E)}$$

Bayes' Theorem

- $H_1$ : The car is behind Door A
- $H_2$ : The car is behind Door B
- $H_3$ : The car is behind Door C

Before any doors are opened, the probabilities of the car being behind each door are equal

Priors

$$P(H_1) = P(H_2) = P(H_3) = \frac{1}{3}$$

# Example 1 – Monty Hall: A Bayesian Approach



The **evidence** is that the host opens Door B, revealing a goat. The **likelihood** depends on where the car is:

**Likelihood**  $P(E | H)$

- If  $H_1$  (car is behind Door A ):  $P(E | H_1) =$
- If  $H_2$  (car is behind Door B ):  $P(E | H_2) =$
- If  $H_3$  (car is behind Door C ):  $P(E | H_3) =$

# Example 1 – Monty Hall: A Bayesian Approach



The **evidence** is that the host opens Door B, revealing a goat. The **likelihood** depends on where the car is:

**Likelihood**  $P(E | H)$

- If  $H_1$  (car is behind Door A ):  $P(E | H_1) = \frac{1}{2}$
- If  $H_2$  (car is behind Door B ):  $P(E | H_2) = 0$
- If  $H_3$  (car is behind Door C ):  $P(E | H_3) = 1$

The **total probability** of the evidence is computed by summing over all H:

$$P(E) = P(E | H_1) P(H_1) + P(E | H_2) P(H_2) + P(E | H_3) P(H_3)$$
$$P(E) = \frac{1}{2}$$

# Example 1 – Monty Hall: A Bayesian Approach



Posterior Probabilities

Bayes' Theorem

$$P(H_1 | E) = \frac{P(E|H_1)P(H_1)}{P(E)} =$$

$$P(H_3 | E) = \frac{P(E|H_3)P(H_3)}{P(E)} =$$

# Example 1 – Monty Hall: A Bayesian Approach



Posterior Probabilities

Bayes' Theorem

$$P(H_1 | E) = \frac{P(E|H_1)P(H_1)}{P(E)} = \frac{\frac{1}{2} \cdot \frac{1}{3}}{\frac{1}{2}} = \frac{1}{3}$$

$$P(H_3 | E) = \frac{P(E|H_3)P(H_3)}{P(E)} = \frac{1 \cdot \frac{1}{3}}{\frac{1}{2}} = \frac{2}{3}$$

**Switch** to maximize your chances of winning

# Conditional and Total Probabilities



The conditional probability of  $A$  given  $B$ , denoted as  $P(A | B)$ , is defined as:

$$P(A | B) = \frac{P(A \cap B)}{P(B)} \quad \text{if } P(B) > 0$$

Similarly, the conditional probability of  $B$  given  $A$ , denoted as  $P(B | A)$ , is:

$$P(B | A) = \frac{P(A \cap B)}{P(A)} \quad \text{if } P(A) > 0$$

We can relate these conditional probabilities by first writing the joint probability of selecting

Since  $P(A \cap B)$  is symmetric (the event "  $A$  and  $B$  " is the same as "  $B$  and  $A$  " ),

# Conditional and Total Probabilities



To express  $P(A | B)$  in terms of  $P(B | A)$ , rearrange the equation:

$$P(A | B) = \frac{P(B | A)P(A)}{P(B)}$$

Using the law of total probability if A is part of a partition of the sample space.

$$P(A_i | B) = \frac{P(B|A_i)P(A_i)}{\sum_{j=1}^n P(B|A_j)P(A_j)}$$

# Example 2 - Cousin's Gender



Your distant cousin has two kids with genders equally likely to occur.

- What is the probability that both are girls?
- If you remember that one is a girl, what the probability that both are girls?

$$(a) \quad \{XX, XX\} \quad \{XX, XY\} \quad \{XY, XY\} \quad \{XY, XX\}$$

$$P(a = XX, b = XX) = \frac{1}{4}$$

$$(b) \quad P(b = XX \mid a = XX) = \frac{1}{3}$$

# Mammogram Problem



- Let's say 1% of women have breast cancer
- Suggesting that 99% of women do not

$$P(\text{ cancer } ) = 0.01$$
$$P(\text{ no cancer } ) = 0.99$$

- And let's say 80% of mammograms detect breast cancer when it is there (true positive)
- Suggesting that 20% miss the cancer (false negative)

## Conditional Probabilities

$$P(\text{test positive} \mid \text{cancer}) = 0.80$$
$$P(\text{test negative} \mid \text{cancer}) = 0.20$$

- And let's say 9.6% of mammograms detect breast cancer when it is not there (false positive)
- Suggesting that 90.4% correctly return a negative result (true negative)

$$P(\text{test positive} \mid \text{no cancer}) = 0.096$$
$$P(\text{test negative} \mid \text{no cancer}) = 0.904$$

# The question



## Question

If a woman at age 40 is tested as positive, what is the probability that she indeed has breast cancer?

0% – 30%    30% – 60%    60% – 100%

## Answer

If a woman at age 40 is tested as positive, what is the probability that she indeed has breast cancer?

0% – 30%     30% – 60%     60% – 100%

# The Doctors' Answers



## Question

Why is the actual probability lower?



95 doctors out of 100

said the answer is between 70% to 80%

# Mammogram Problem – Ven Diagram



V5



Given that a woman tested positive.

What is the probability she has cancer?

- a woman with breast cancer
- a woman without breast cancer
- a woman with positive mammography

# Mammogram Problem – Bayes' Theorem



$$P(\text{cancer} \mid \text{test positive}) =$$

$$= \frac{P(\text{test positive} \mid \text{cancer})P(\text{cancer})}{P(\text{test positive})}$$

$$= \frac{(0.8)(0.01)}{(0.8)(0.01) + (0.096)(0.99)} = 0.0776$$

$$P(B \cap C) = P(B \mid C)P(C)$$



$$P(B \cap \bar{C}) = P(B)$$

8 OUT OF 100 PEOPLE WHO TEST POSITIVE  
HAVE CANCER

# Mammogram Problem – Total Probability



$$\begin{aligned} P(\text{no cancer} \mid \text{test positive}) &\quad \curvearrowright \quad P(A \mid B) = 1 - P(\bar{A} \mid B) \\ &= \frac{P(\text{test positive} \mid \text{no cancer})P(\text{no cancer})}{P(\text{test positive})} \\ &= \frac{(0.096)(0.99)}{(0.096)(0.99) + (0.80)(0.01)} = 0.9224 \end{aligned}$$

Shortcut:  $P(\text{no cancer} \mid \text{test positive}) = 1 - P(\text{cancer} \mid \text{test positive})$

# Example 3 – Highway Safety



- A recent highway safety study found that 77% of accidents the driver was wearing a seat belt.
- Accident reports indicated that 92% of those drivers escaped serious injury but only 63% of the non-belted drivers were so fortunate.

What is the probability that a driver who was seriously injured wasn't wearing a belt?

Let  $B$ : wearing a belt,  $P$ : serious injury

$$P(B) = 0.77 \quad P(\bar{I} | B) = 0.92$$

$$\Rightarrow P(\bar{I} | \bar{B}) = 0.63$$

$$P(\bar{B} | I) = ?$$

# Example 3 – Continued



$$P(\bar{B} | I) = \frac{P(I | \bar{B})P(\bar{B})}{P(I)}$$

$P(I | \bar{B}) = 0.37$

$P(I \cap \bar{B}) = P(I | \bar{B})P(\bar{B})$   
 $= (1 - 0.63)(1 - 0.72)$

$P(I) = P(I \cap B) + P(I \cap \bar{B})$

$$= \frac{(1 - 0.63)(1 - 0.77)}{(1 - 0.63)(1 - 0.77) + (1 - 0.92) \times 0.77}$$

$P(\bar{B} | I) = 0.58$

# Example 4 – Updating Probabilities 1



## Biased Coin Toss Problem

We have two coins, one fair (C) and one biased (Cb).

- The probability of tossing heads with the fair coin is 50%.
- The probability of tossing heads with the biased coin,  $P(H|Cb) = 0.75$ .

# Example 4 – Continued



Fair Coin

$$P(H) = 0.5$$

$$P(C, H) = P(C) \times P(H)$$

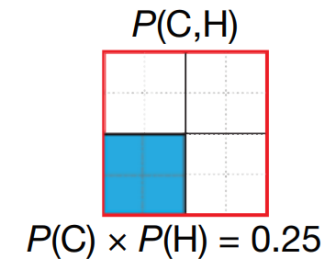
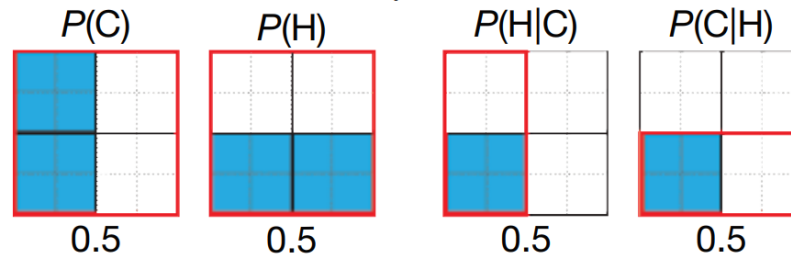
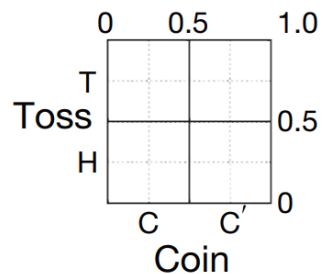
Marginal, conditional and joint probabilities

Marginal (individual)

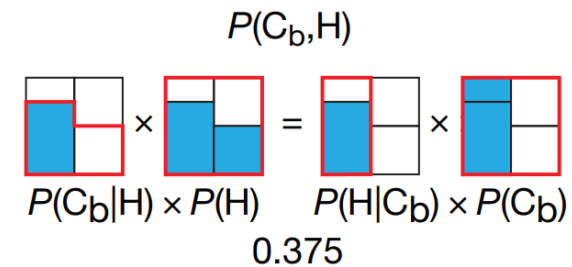
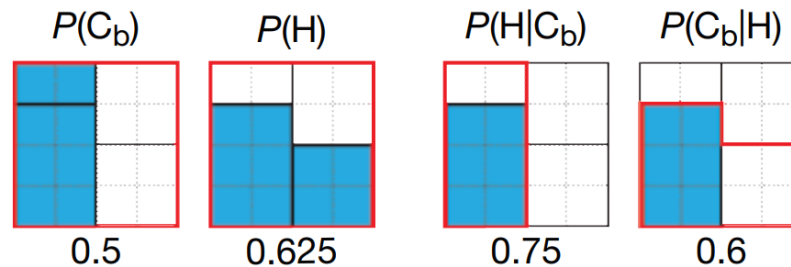
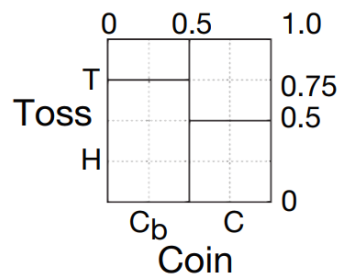
Conditional

Joint

Independent events



Dependent events



# Example 4 – Continued



Biased coin towards heads

$$P(H | C) = 0.5 \text{ and } P(H | C_b) = 0.75$$

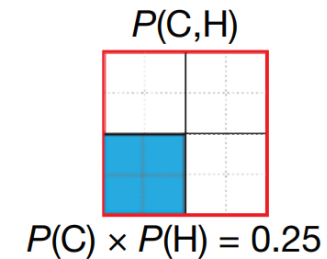
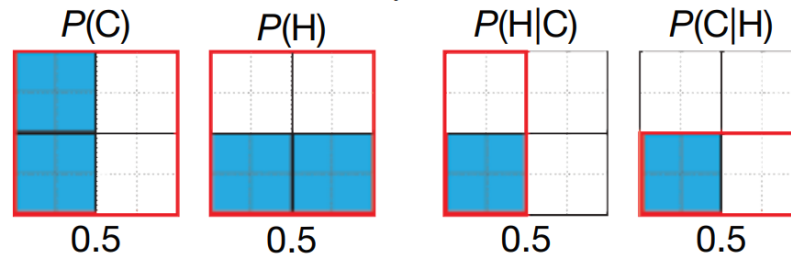
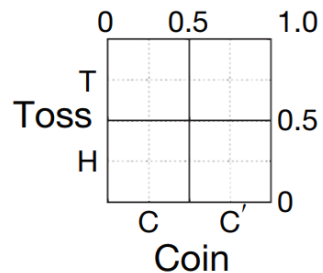
Marginal, conditional and joint probabilities

Marginal (individual)

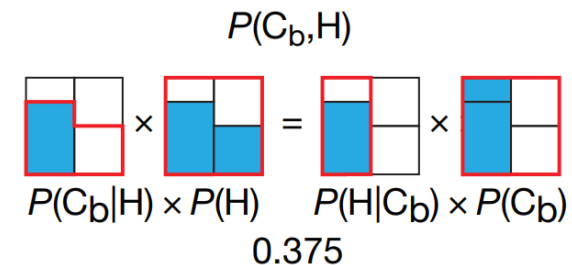
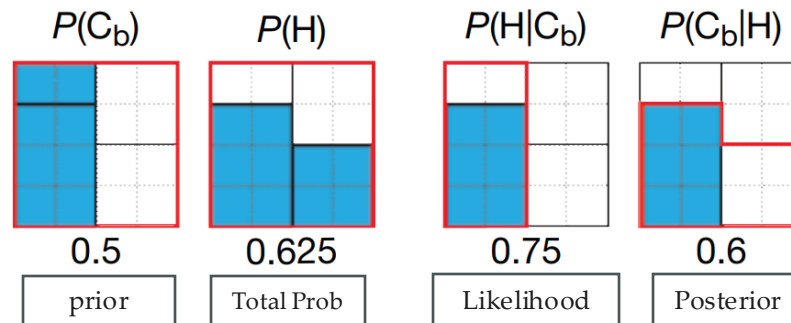
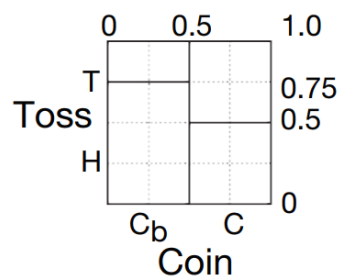
Conditional

Joint

Independent events



Dependent events



Leads to Bayes Theorem

Conditional Probabilities

# Example 4 – Continued



## Biased Coin

If we select a coin at random, we can use Bayes' theorem to calculate the probability that the coin we selected was the biased one, given outcome of tosses.

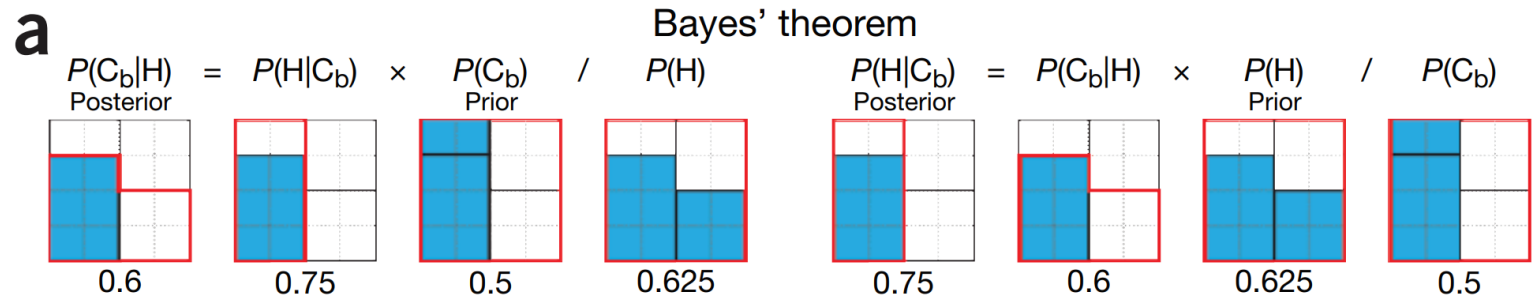
### Posterior

$$P(C_b | H) = \frac{P(H|C_b) \times P(C_b)}{P(H)}$$

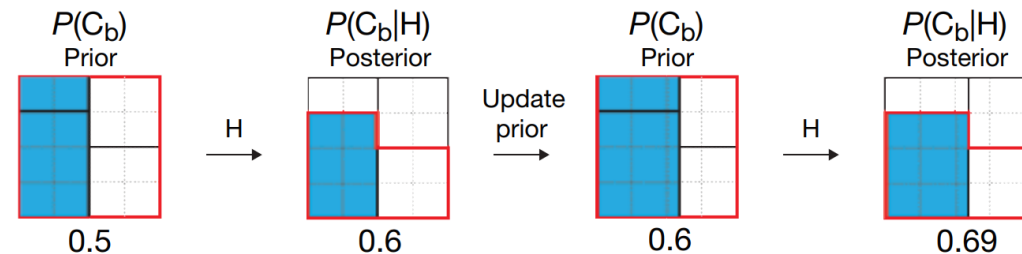
$$P(C_b | H) = \frac{0.75 \times 0.5}{0.625}$$

### Probability of observing heads

$$\begin{aligned} P(H) &= P(H | C) \times P(C) + P(H | C_b) \times P(C_b) \\ &= 0.5 \times 0.5 + 0.75 \times 0.5 = 0.625 \end{aligned}$$



### **b** Updating priors and iterative estimation of probabilities



# Example 4 – Continued



| <i>toss</i> | <i>toss outcome</i><br>0 = tail, 1 = head | <i>posterior</i><br>P(Cb   H) | <i>likelihood</i><br>P(H   Cb) | <i>prior</i><br>P(Cb) | P(H)  |
|-------------|---|-------------------------------|--------------------------------|-----------------------|-------|
| 1           | 1   | 0.600                         | 0.75                           | 0.500                 | 0.625 |
| 2           | 1   | 0.692                         | 0.75                           | 0.600                 | 0.650 |
| 3           | 1   | 0.771                         | 0.75                           | 0.692                 | 0.673 |
| 4           | 1   | 0.835                         | 0.75                           | 0.771                 | 0.693 |
| 5           | 1   | 0.884                         | 0.75                           | 0.835                 | 0.709 |
| 6           | 1   | 0.919                         | 0.75                           | 0.884                 | 0.721 |
| 7           | 1   | 0.945                         | 0.75                           | 0.919                 | 0.730 |
| 8           | 1   | 0.962                         | 0.75                           | 0.945                 | 0.736 |
| 9           | 1   | 0.975                         | 0.75                           | 0.962                 | 0.741 |
| 10          | 1   | 0.983                         | 0.75                           | 0.975                 | 0.744 |
| 11          | 1   | 0.989                         | 0.75                           | 0.983                 | 0.746 |
| 12          | 1   | 0.992                         | 0.75                           | 0.989                 | 0.747 |

# Example 5 – Disease and Genomic Markers



## Patient's Disease

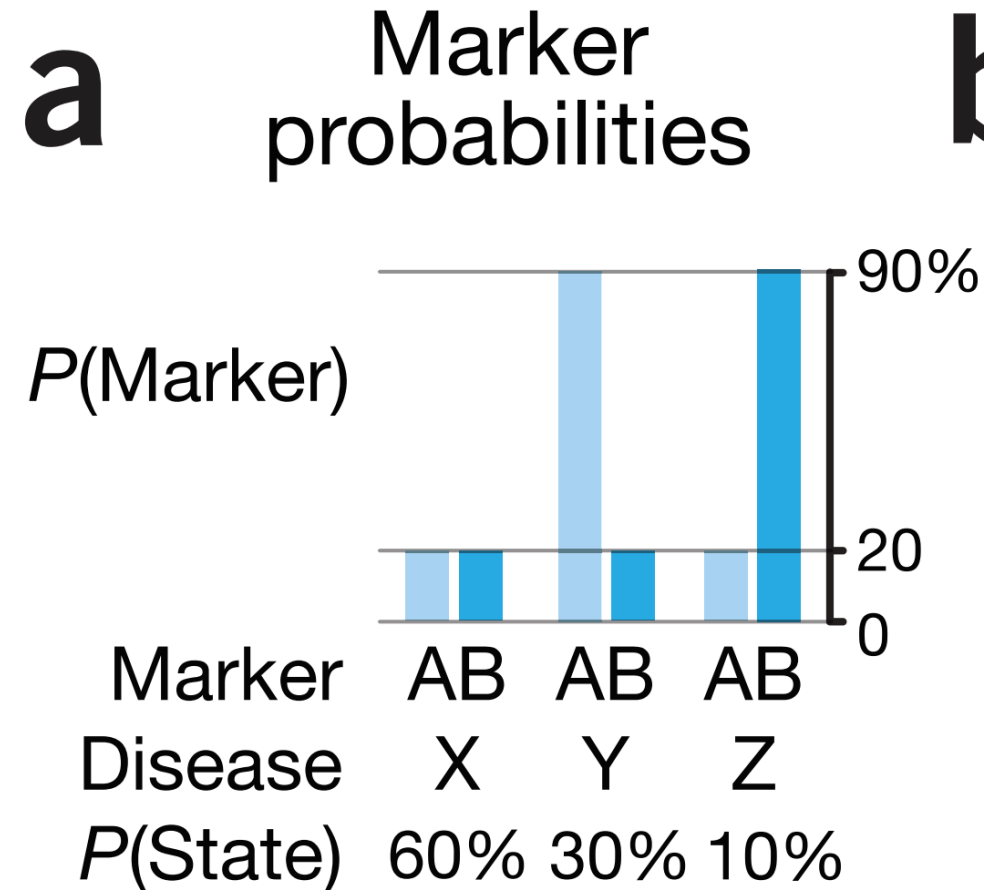
We have three diseases  $D = \{X, Y, Z\}$  and two biomarkers  $M = \{A, B\}$ .

- The probability to **find a given marker** in the blood of a patient with a **disease is given** in the first table below.
- Using Bayes' theorem, we can calculate the probability that the **patient has a given disease having observed one of the markers in their blood.**

# Example 5 – Continued



| <i>Disease</i> | P(disease) | <i>Predicted marker</i> |          |
|----------------|------------|-------------------------|----------|
|                |            | <b>A</b>                | <b>B</b> |
| <b>X</b>       | 0.6        | 0.2                     | 0.2      |
| <b>Y</b>       | 0.3        | 0.9                     | 0.2      |
| <b>Z</b>       | 0.1        | 0.2                     | 0.9      |

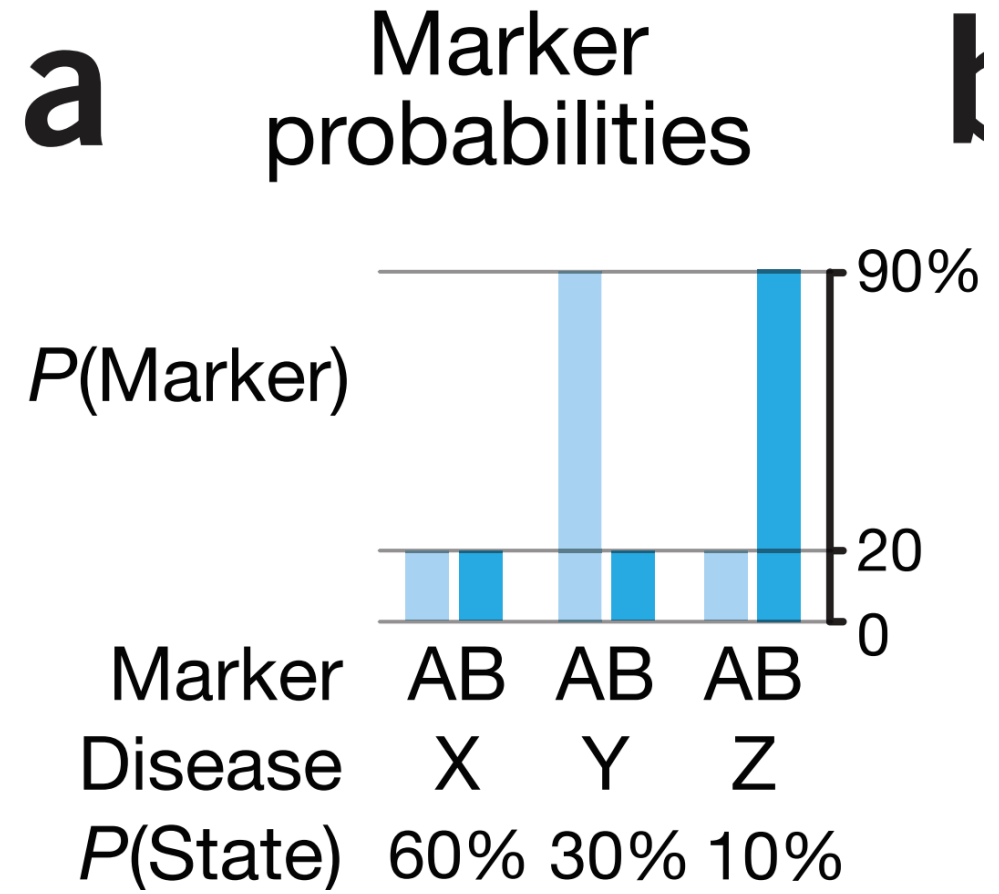


# Example 5 – Continued



| <i>Disease</i> | P(disease) | <i>Predicted marker</i> |          |
|----------------|------------|-------------------------|----------|
|                |            | <b>A</b>                | <b>B</b> |
| <b>X</b>       | 0.6        | 0.2                     | 0.2      |
| <b>Y</b>       | 0.3        | 0.9                     | 0.2      |
| <b>Z</b>       | 0.1        | 0.2                     | 0.9      |

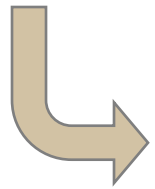
$P(M | D)$



# Example 5 – Continued



Probability of disease given that a marker is observed.



$$P(D | M) = \frac{P(M|D) \times P(D)}{P(M)}$$

Bayes' Theorem

The probability of disease X given that marker A is observed.



$$P(X | A) = \frac{P(A|X) \times P(X)}{P(A)}$$

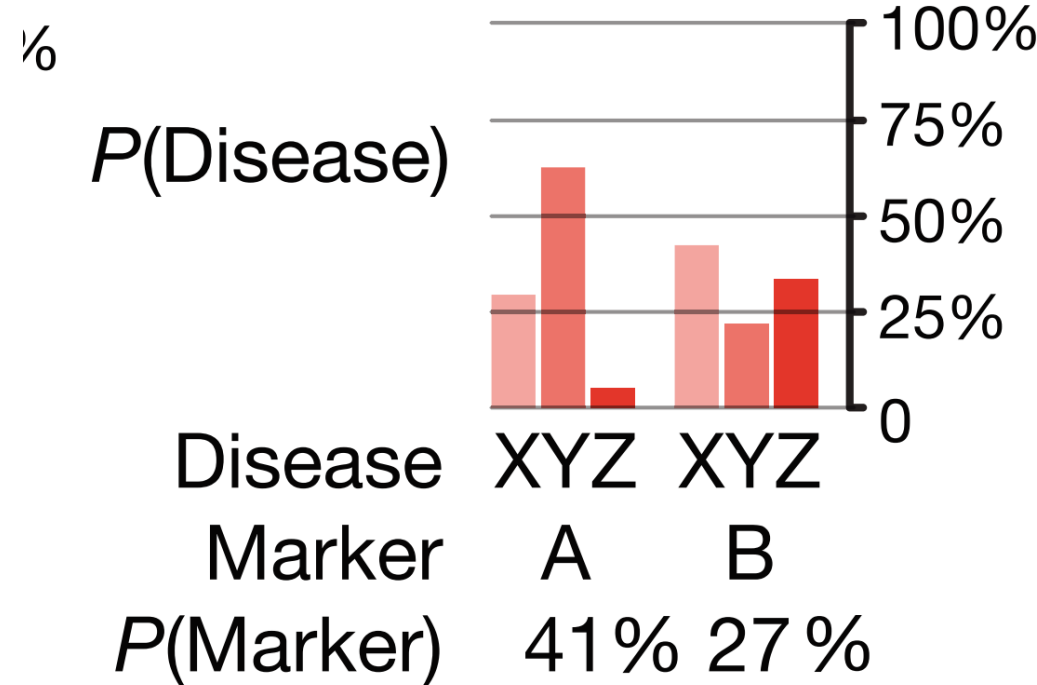
# Example 5 – Continued



$$P(A | X) = 0.2 \quad \leftarrow \quad P(X) = 0.6$$
$$P(X | A) = \frac{P(A|X) \times P(X)}{P(A)}$$
$$P(A) = 0.6 \times 0.2 + 0.3 \times 0.9 + 0.1 \times 0.2 = 0.41$$

$$P(X | A) = 0.2 \times 0.6 / 0.41 = 0.29$$

## b Disease prediction with one observation



# Example 5 – Continued: Observation 2



If marker A is found, the most likely disease is Y (65.9%).

| <i>Disease</i> | Likelihood<br>$P(A d)$ | Prior<br>$P(d)$ | $P(A) =$<br>0.41     | Posterior |
|----------------|------------------------|-----------------|----------------------|-----------|
|                |                        |                 | $P(A d) \times P(d)$ | $P(d A)$  |
| X              | 0.2                    | 0.6             | 0.12                 | 0.29      |
| Y              | 0.9                    | 0.3             | 0.27                 | 0.66      |
| Z              | 0.2                    | 0.1             | 0.02                 | 0.05      |

# Example 5 – Continued: Observation 2



Having observed A , we could refine our predictions by testing for B.

- We use the posterior probability of the disease after observing A as the new prior.

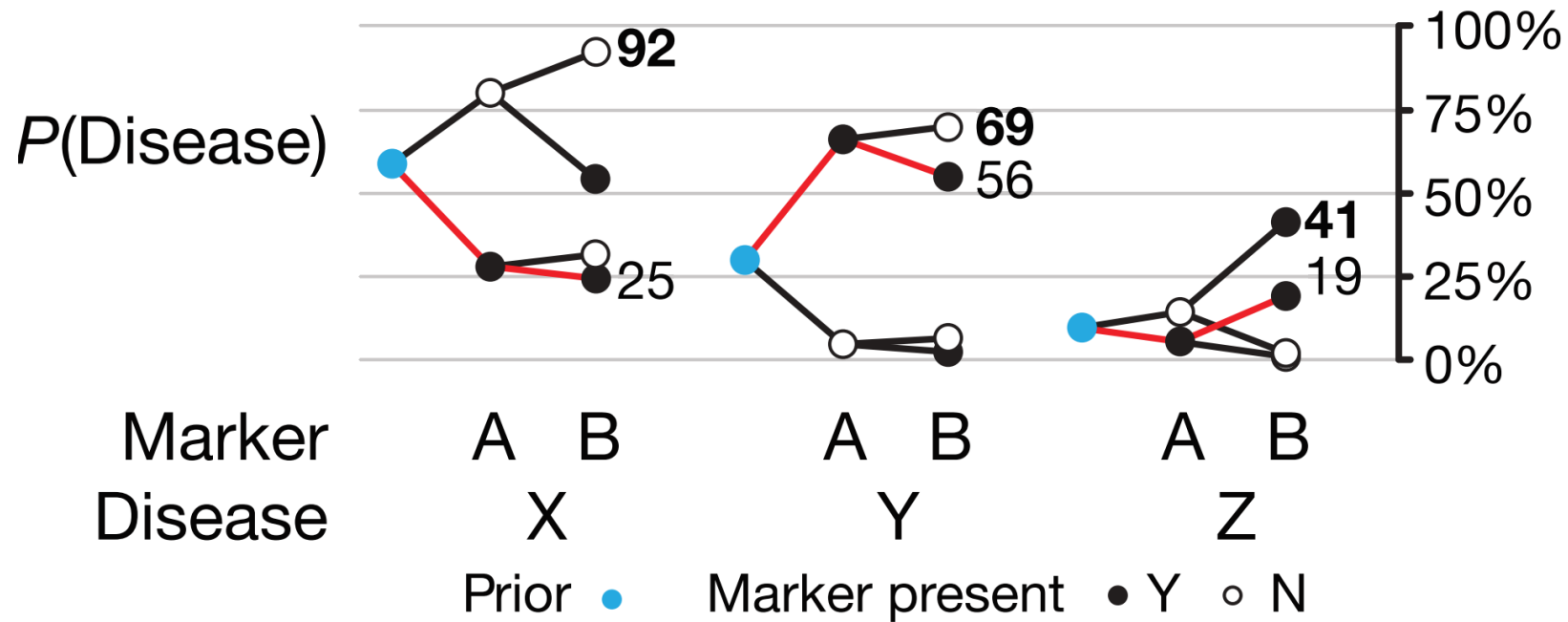
| <i>Disease</i> | Likelihood<br>$P(B   d)$ | Prior<br>$P(d)$ | $P(B) =$<br>0.23       | Posterior  |
|----------------|--------------------------|-----------------|------------------------|------------|
|                |                          |                 | $P(B   d) \times P(d)$ | $P(d   B)$ |
| <b>X</b>       | 0.2                      | 0.29            | 0.06                   | 0.25       |
| <b>Y</b>       | 0.2                      | 0.66            | 0.04                   | 0.56       |
| <b>Z</b>       | 0.9                      | 0.05            | 0.23                   | 0.19       |

# Example 5 – Continued: Observation 2



## C

### Disease prediction with two observations



# Next: Discrete Random Variables

